

1 Extended Ninja Virtual Machine

theory *JBC-Semantics* = *Form*:

setup « [Simplifier.change-simpset-of op setmksimps (setmp proofs 2 (mksimps mksimps-pairs))] »

1.1 States and Program Syntax

record *env* =
cs::heap list
lv::var \Rightarrow *val option*

types
jbc-state = *pos* \times *jvm-state* \times *env*

types
jbc-prog = *jvm-prog* \times (*pos* $\sim\sim>$ *expr*)

1.2 Auxiliary functions

constdefs
incA::pos \Rightarrow *pos*
incA $\equiv \lambda(C,M,n).$ (*C,M,n+1*)

constdefs
cmd::jbc-prog \Rightarrow *pos* \Rightarrow *instr option*
cmd $\equiv \lambda(P,A).$ (*C,M,pc*). case class *P C* of *None* \Rightarrow *None*
| *Some c* \Rightarrow (case (map-of (snd (snd *c*)) *M*)
of *None* \Rightarrow *None*
| *Some m* \Rightarrow (let *is=fst* (snd (snd (snd (snd *m*))))
in (if *pc < length is* then *Some (is!pc)* else *None*)))

consts
domMC::(cname \times *mname* \times *jvm-method*) \Rightarrow *pos list*

recdef *domMC measure* ($\lambda x.0$)
domMC (*C,M,(mxs,mxl,bd,et)*) = *map* ($\lambda n.$ (*C,M,n*)) (*upt 0 (length bd)*)

consts
domCC::jvm-method cdecl \Rightarrow *pos list*

recdef *domCC measure* ($\lambda(C,cd).$ *length (snd (snd cd))*)
domCC (*C,(C',fs,[])*) = []
domCC (*C,(C',fs,(M,Ts,T,m) # ms)*) = *domMC* (*C,M,m*) @ (*domCC* (*C,(C',fs,ms)*))

```

constdefs
 $domC::jbc\text{-}prog \Rightarrow pos\ list$ 
 $domC\ \Pi \equiv concat\ (map\ domCC\ (fst\ \Pi))$ 

constdefs
 $anF::jbc\text{-}prog \Rightarrow pos \Rightarrow expr\ option$ 
 $anF \equiv \lambda(P,An)\ p.\ An\ ?\ p$ 

consts
 $hasAn::jbc\text{-}prog \Rightarrow pos \Rightarrow bool$ 
defs  $hasAn\text{-}def$  [simp]:
 $hasAn\ \Pi\ p \equiv (case\ anF\ \Pi\ p\ of\ None \Rightarrow False\ |\ Some\ a \Rightarrow True)$ 

constdefs  $aF::jbc\text{-}prog \Rightarrow pos \Rightarrow expr$ 
 $aF\ \Pi\ p \equiv (case\ anF\ \Pi\ p\ of\ None \Rightarrow TT\ |\ Some\ A \Rightarrow A)$ 

constdefs
 $domA :: jbc\text{-}prog \Rightarrow pos\ list$ 
 $domA \equiv (\lambda\ \Pi.[p \in domC\ \Pi.\ hasAn\ \Pi\ p])$ 

consts
 $invokes::instr\ option \times pos \Rightarrow bool$ 

recdef  $invokes\ \{\}$ 
— invokes (ins,(C,M,p)) checks whether ins calls method M.
 $invokes\ (Some\ (Invoke\ Mn\ n),(C,M,pc)) = (Mn=M)$ 
 $invokes\ (instr,p) = False$ 

constdefs
 $callers::jbc\text{-}prog \Rightarrow pos \Rightarrow pos\ list$ 
 $callers\ \Pi\ p \equiv [cp \in (domC\ \Pi).\ invokes\ ((cmd\ \Pi\ cp),p)]$ 

constdefs  $classnames::jvm\text{-}prog \Rightarrow cname\ list$ 
 $classnames\ P \equiv map\ fst\ P$ 

constdefs  $has\text{-}method::jvm\text{-}prog \Rightarrow cname \Rightarrow mname \Rightarrow bool$ 
 $has\text{-}method\ P\ C\ M \equiv (C,M)\ mem\ (methodnames\ P)$ 

```

1.3 Operational Semantics

```

constdefs
 $Start :: cname$ 
 $Start \equiv "Start"$ 
 $main :: mname$ 
 $main \equiv "main"$ 

```

```
constdefs ipc::jbc-prog  $\Rightarrow$  pos
ipc P  $\equiv$  (Start,main,0)
```

1.4 Transition Relation

```
consts
effS::jbc-prog  $\Rightarrow$  (jbc-state  $\times$  jbc-state) set
```

— Note: In case of an uncaught exception this semantics halts, whereas the JVM Semantics halts and empties the framestack.

```
inductive effS  $\Pi$ 
intros
```

expt:

```
¶ P = fst  $\Pi$ ; p = (C,M,pc); i = instrs-of P C M ! pc;
 $\sigma$  = (None,h,(stk,loc,p)#frs);
has-method P C M;
exec-instr i P h stk loc C M pc frs = (Some xa,h',bla);
find-handler P xa h ((stk,loc,p)#frs) =  $\sigma'$ ;
 $\sigma'$  = (None,h,([Addr xa],loc',p')#frs');
e' = e(cs:=drop (length frs - length frs') (cs e))
]  $\implies$  ((p, $\sigma$ ,e),(p', $\sigma'$ ,e'))  $\in$  effS  $\Pi$ 
```

nrmrl:

```
¶ P = fst  $\Pi$ ; p = (C,M,pc); i = instrs-of P C M ! pc;
 $\sigma$  = (None,h,(stk,loc,p)#frs);
has-method P C M;
exec-instr i P h stk loc C M pc frs = (None,h',fr'#frs');
 $\sigma'$  = (None,h',fr' # frs');
p' = snd (snd fr');
e' = e(cs:=if  $\exists$  M n. i = Invoke M n then h#(cs e)
      else if i = Return then tl (cs e) else cs e)
]  $\implies$  ((p, $\sigma$ ,e),(p', $\sigma'$ ,e'))  $\in$  effS  $\Pi$ 
```

constdefs

```
initS ::jbc-prog  $\Rightarrow$  jbc-state set
initS  $\Pi$   $\equiv$  { (p, $\sigma$ ,e) . p = ipc  $\Pi$   $\wedge$   $\sigma$  = start-state (fst  $\Pi$ ) (fst (ipc  $\Pi$ )) (fst (snd (ipc  $\Pi$ )))  $\wedge$  cs e =
[] }
```

consts Reachables::jbc-prog \Rightarrow jbc-state set

```

inductive Reachables  $\Pi$ 
intros
init:  $\llbracket s \in initS \Pi \rrbracket \implies s \in Reachables \Pi$ 
step:  $\llbracket s \in Reachables \Pi; (s,s') \in effS \Pi \rrbracket$ 
       $\implies s' \in Reachables \Pi$ 

```

1.5 Auxiliary Lemmas

lemma *sees-field-class*:

$$P \vdash Cl \text{ sees } F:T \text{ in } Cl' \implies \text{is-class } P \text{ } Cl$$

lemma *domCC-split*:

$$\text{domCC } (C, (S, fs, ms @ ms')) = \text{domCC } (C, (S, fs, ms)) @ \text{domCC } (C, (S, fs, ms'))$$

lemma *cmd-domC*:

$$\bigwedge p \Pi \text{ instr. } cmd \Pi p = \text{Some instr} \implies p \in \text{set } (\text{domC } \Pi)$$

lemma *domC-cmd*:

$$p \notin \text{set } (\text{domC } \Pi) \implies cmd \Pi p = \text{None}$$

lemma *domCC-split-parts*:

$$(C, M, pc) \in \text{set } (\text{domCC } (C', S, Fs, Ms)) \implies \exists Ms' Ms'' Ts T mxs m xl is et. Ms = Ms' @ (M, Ts, T, (mxs, m xl, is, et)) \# Ms'' \wedge (C, M, pc) \in \text{set } (\text{domMC } (C', M, m xs, m xl, is, et))$$

lemma *domCC-map*:

$$\text{domCC } (C, C', fs, ms) = \text{concat } (\text{map } (\lambda (M, Ts, T, m). \text{domMC } (C, M, m)) ms)$$

lemma *domMC-props*:

$$\bigwedge m. (C, M, pc) \in \text{set } (\text{domMC } (C', M', m)) \implies C = C' \wedge M = M' \wedge pc < \text{length } (\text{fst } (\text{snd } (m)))$$

lemma *domA-simp*:

$$\text{domA} = (\lambda \Pi. [pc \in \text{domC } \Pi. \text{anF } \Pi. pc \neq \text{None}])$$

lemma *effS-Reachables*:

$$s \in Reachables \Pi = (\exists s0. s0 \in initS \Pi \wedge (s0, s) \in (effS \Pi)^*)$$

lemma *check-inv*:

assumes *wt:wf-jvm-prog_k* P

assumes *initial:σ = start-state P C M* \wedge $(P \vdash C \text{ sees } M : [] \rightarrow T = m \text{ in } C)$

assumes *reachable:P ⊢ σ -jvm→ σ'*

shows *check P σ'*

end